

# Constraints

## Engineering Mechanics: Dynamics

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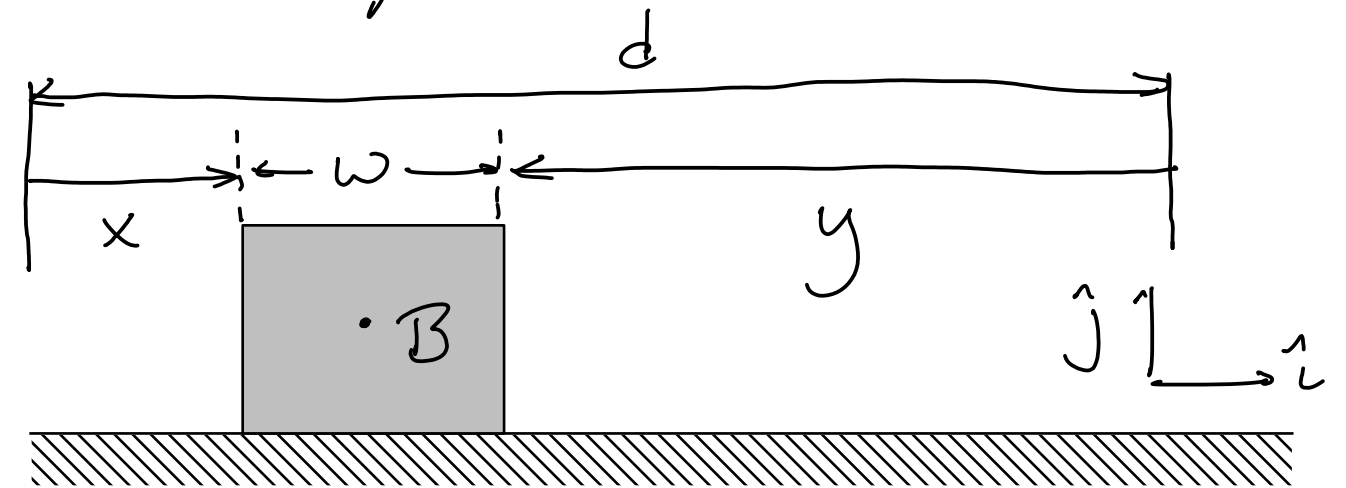


**Kinematics:** Consideration of the **allowable motion** of an object, consistent with the **constraints** that act on that object, without regard to the forces that produce motion or the motion that actually occurs

- RESTRICTIONS ON THE ALLOWABLE MOTION
- IMPOSE A RELATIONSHIP BETWEEN COORDINATES

$$x(t) + w + y(t) = d$$

$$y(t) = (d - w) - x(t)$$



CONSTRAINTS CAN BE IDENTIFIED  
FROM VELOCITIES

$$\begin{aligned} \underline{v}_B &= \dot{x} \hat{i} \\ &= -\dot{y} \hat{i} \end{aligned}$$

$$\int_0^t \{ \dot{x} = -\dot{y} \} dt$$

$$x(t) - x(0) = - (y(t) - y(0))$$

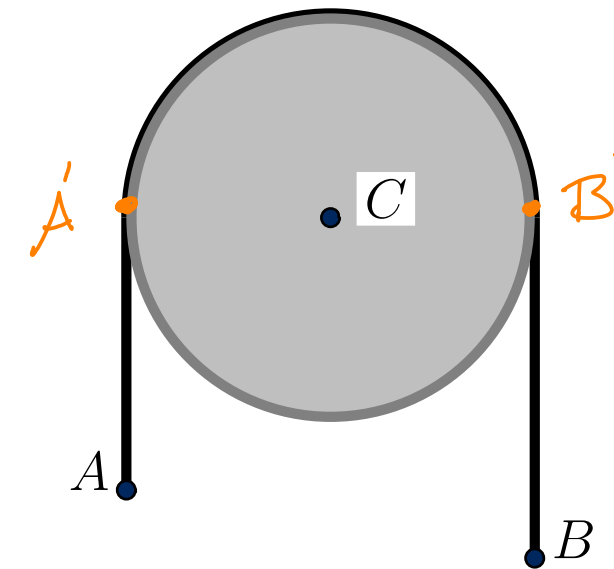
$$\begin{aligned} y(t) &= -x(t) + (y(0) + x(0)) \\ &= -x(t) + (d - w) \end{aligned}$$

# Pulleys

$$\underline{v}_A = \underline{v}_C + \underline{\omega}_P \times \underline{r}_{A/C}$$

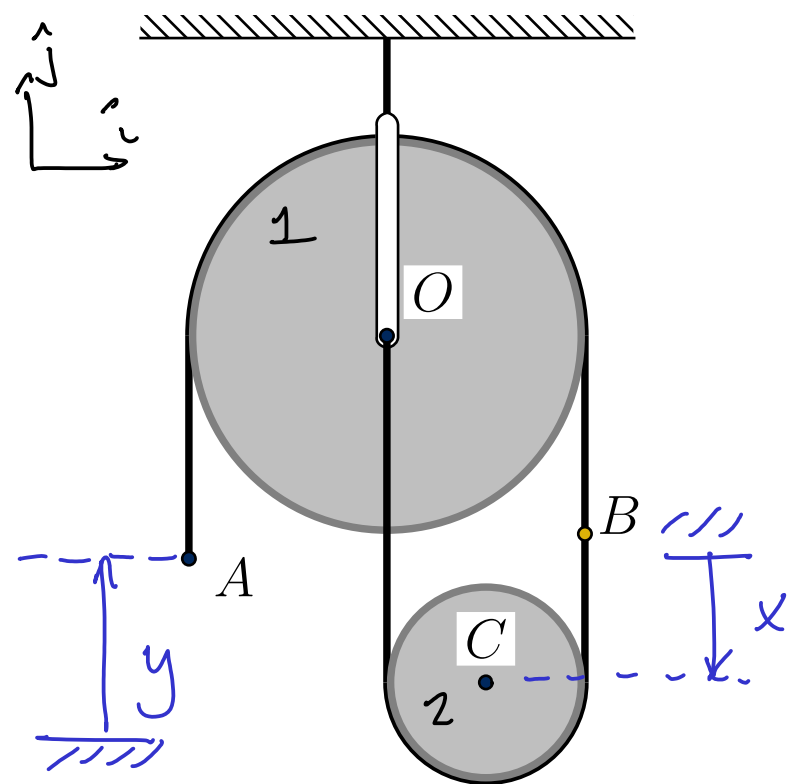
$$\underline{v}_B = \underline{v}_C + \underline{\omega}_P \times \underline{r}_{B/C}$$

$$\underline{r}_{A/C} = -\underline{r}_{B/C}$$



$$\underline{v}_A + \underline{v}_B = 2\underline{v}_C$$

$$\underline{v}_B - \underline{v}_A = 2\underline{\omega}_P \times \underline{r}_{B/C}$$



ON 1:

$$\underline{v}_A + \underline{v}_B = 2\underline{v}_O$$

$$\underline{v}_O + \underline{v}_B = 2\underline{v}_C$$

$$\underline{v}_A + (2\underline{v}_C) = \underline{0} \rightarrow \underline{v}_C = -\frac{\underline{v}_A}{2}$$

$$(-\dot{x}\hat{j}) = -\frac{(\dot{y}\hat{j})}{2}$$

$$\dot{x} = \frac{\dot{y}}{2} \rightarrow \boxed{x = \frac{y}{2}}$$

# Rolling

NO SLIP IMPLIES THE CONTACT POINTS  
HAVE THE SAME VELOCITY

$$\underline{v}_{C_{\text{DISK}}} = \underline{v}_{C_{\text{GROUND}}} = \underline{0}$$

$$\underline{v}_g = \underline{v}_c + \underline{\omega} \times \underline{r}_{g/c}$$

$$\begin{aligned} (\dot{x} \hat{i}) &= \underline{0} + (\dot{\theta} \hat{k}) \times (r \hat{j}) \\ &= (-r \dot{\theta}) \hat{i} \end{aligned}$$

$$\dot{x} = -r \dot{\theta}$$

$$\int_0^t \left\{ \ddot{x} = -r \ddot{\theta} \right\} dt$$

$$x(t) - x(0) = -r (\theta(t) - \theta(0))$$

$$x(t) = -r \theta(t) + (x(0) + r \theta(0))$$

MEASURING FROM A COMMON CONFIGURATION  
 $x(0) + r \theta(0) = 0$

$$x(t) = -r \theta(t)$$

