

# Particle Dynamics

## Engineering Mechanics: Dynamics

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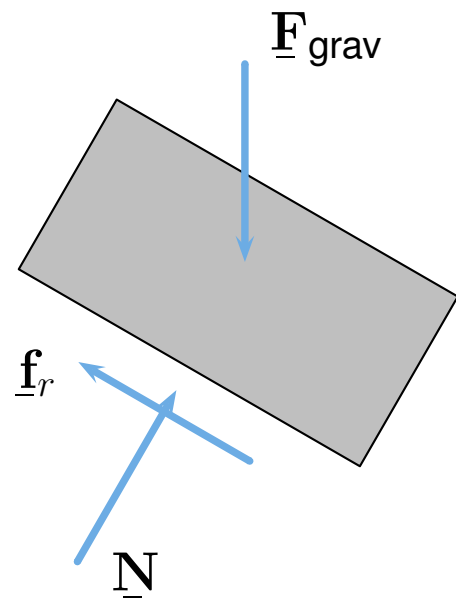
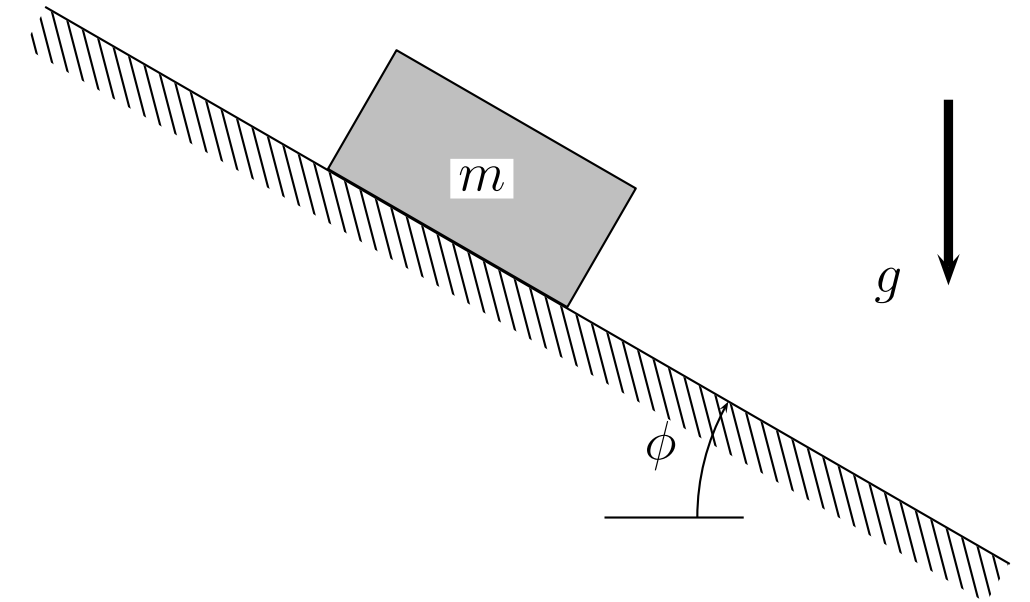
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A block of mass  $m$  is released from rest and slides on a rough surface with coefficient of friction  $\mu$  and inclined at an angle  $\phi$ . What is the minimum angle of inclination  $\phi = \phi_*$  necessary for the block to slide? If  $\phi > \phi_*$  find the acceleration of the block.



The forces acting on the block arise from

- ▶ Weight ( $\underline{F}_{\text{grav}}$ )
- ▶ Normal force ( $\underline{N}$ )
- ▶ Friction ( $\underline{f}_r$ )

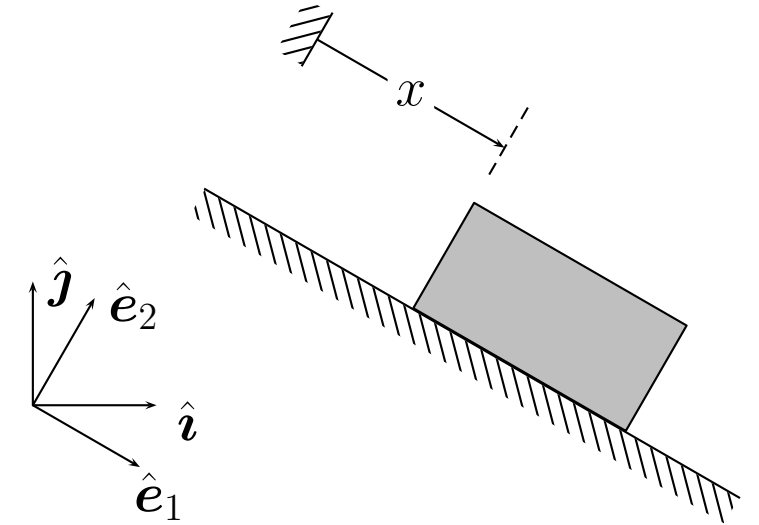
## Coordinates and Directions/Kinematics

The motion of the block is only in the  $\hat{e}_1$  direction, and we measure the displacement of the block as  $x$ . The directions  $(\hat{i}, \hat{j})$  and  $(\hat{e}_1, \hat{e}_2)$  are related as

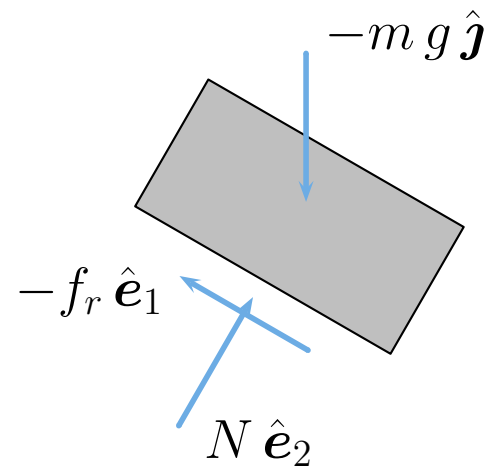
$$\hat{i} = C_\phi \hat{e}_1 + S_\phi \hat{e}_2, \quad \hat{j} = -S_\phi \hat{e}_1 + C_\phi \hat{e}_2.$$

With these, the acceleration of the block is

$$\underline{\mathbf{a}}_B = \ddot{x} \hat{e}_1,$$



## Free Body Diagram/Equations of Motion



Applying linear momentum balance to the block

$$\begin{aligned} \sum \underline{\mathbf{F}} &= -m g \hat{j} - f_r \hat{e}_1 + N \hat{e}_2 = m \ddot{x} \hat{e}_1 = m \underline{\mathbf{a}}_B, \\ (m g S_\phi - f_r) \hat{e}_1 + (-m g C_\phi + N) \hat{e}_2 &= m \ddot{x} \hat{e}_1, \end{aligned}$$

Taking components in the  $(\hat{e}_1, \hat{e}_2)$  directions

$\hat{e}_1$  direction:

$$m g S_\phi - f_r = m \ddot{x},$$

$\hat{e}_2$  direction:

$$-m g C_\phi + N = 0, \quad \longrightarrow \quad N = m g C_\phi.$$

If the block sticks, then  $\ddot{x} \equiv 0$ , so that the required friction force is

$$f_r = m g S_\phi.$$

The magnitude of  $f_r$  must be less than  $\mu N$ , so that

$$\begin{aligned} |f_r| &\leq \mu N, \\ m g S_\phi &\leq \mu m g C_\phi, \quad \longrightarrow \quad \tan \phi \leq \mu. \end{aligned}$$

The critical angle of inclination is  $\phi_\star = \tan^{-1} \mu$ .

For  $\phi > \phi_\star$  the block slides so that  $f_r = \mu N$ , and the acceleration can be solved as

$$\begin{aligned} \ddot{x} &= g S_\phi - \frac{\mu N}{m} = g S_\phi - \mu g C_\phi, \\ \longrightarrow \quad \underline{\mathbf{a}}_B &= \ddot{x} \hat{e}_1 = (g (S_\phi - \mu C_\phi)) \hat{e}_1 \end{aligned}$$

