

# Particle Dynamics

## Engineering Mechanics: Dynamics

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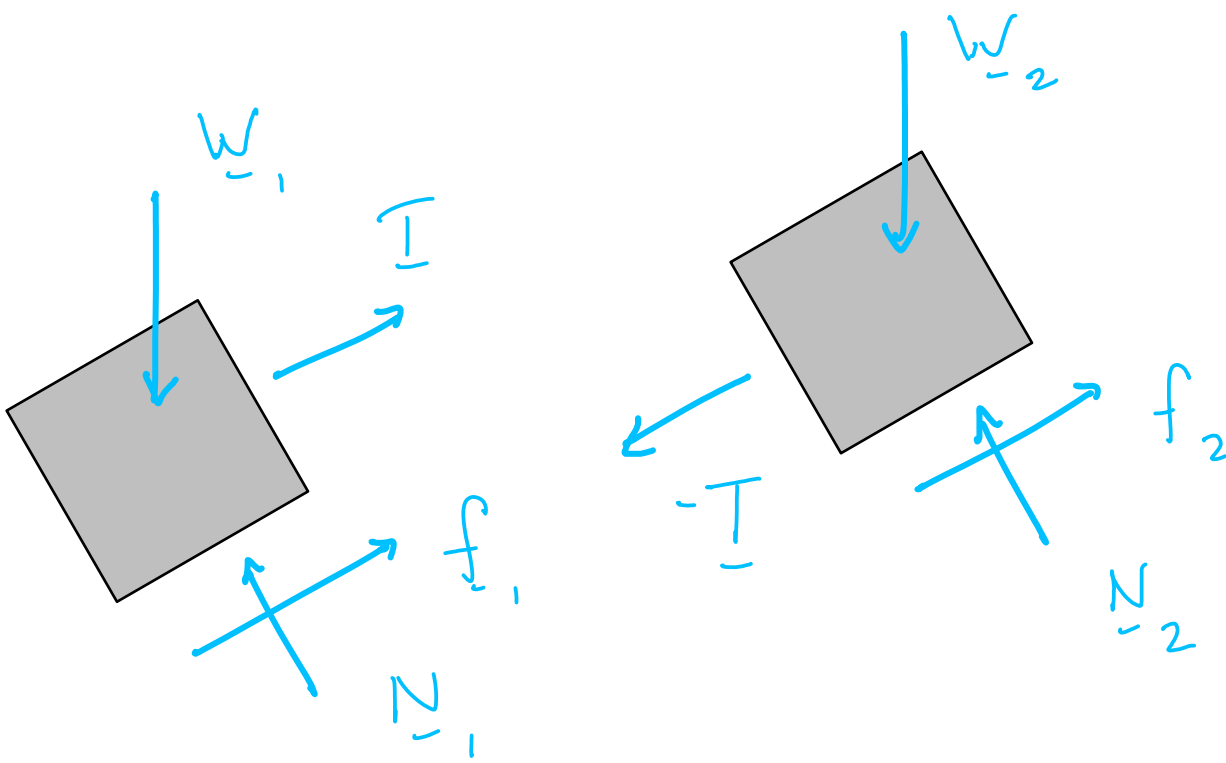
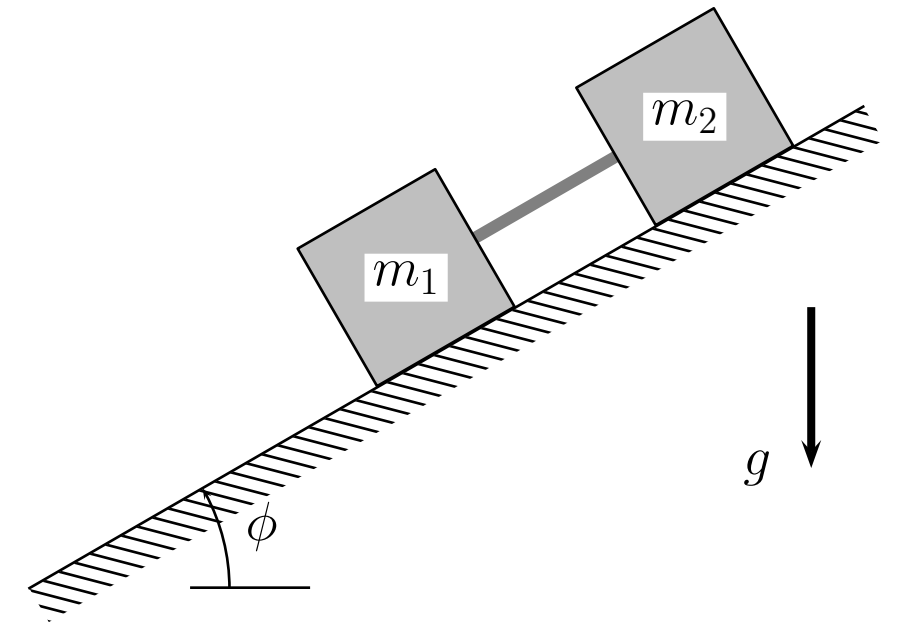
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Two blocks of mass  $m_1$  and  $m_2$  are connected by a massless rod and slide down a rough surface inclined at an angle  $\phi$ . The coefficient of friction between each block and the surface is  $\mu_1$  and  $\mu_2$ . Find the acceleration of the pair and the tension in the rod. What is the minimum angle  $\phi_*$  so that the blocks slide?



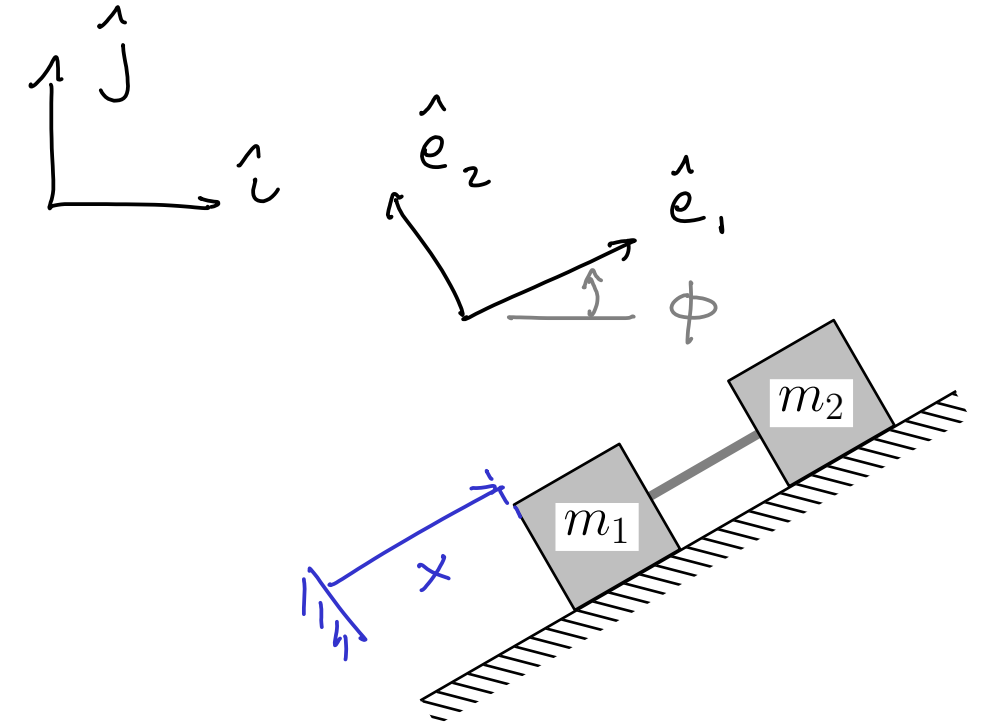
FORCES

- WEIGHT ( $\underline{W}$ )
- NORMAL ( $\underline{N}$ )
- FRICTION ( $\underline{f}$ )
- TENSION ( $\underline{T}$ )

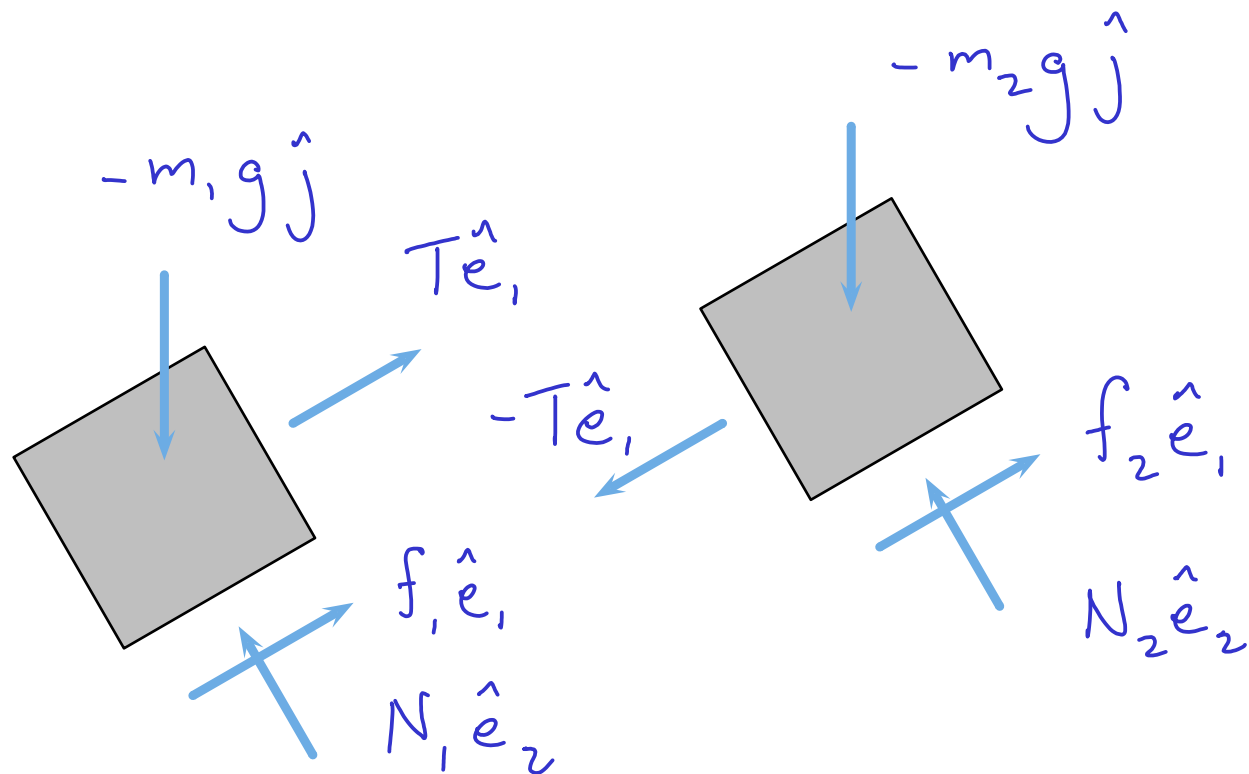
## Coordinates and Directions

$$\hat{i} = C_\phi \hat{e}_1 - S_\phi \hat{e}_2$$

$$\hat{j} = S_\phi \hat{e}_1 + C_\phi \hat{e}_2$$



## Kinematics/Free Body Diagram



ACCELERATION

$$\underline{a}_1 = \underline{a}_2 = \ddot{x} \hat{e}_1$$

Equations of Motion

## LINEAR MOMENTUM BALANCE

BLOCK 1: 
$$-m_1 g \hat{j} + T \hat{e}_1 + f_1 \hat{e}_1 + N_1 \hat{e}_2 = \Sigma \vec{F}_1 = m_1 \vec{a}_1 = m_1 \ddot{x} \hat{e}_1$$

BLOCK 2: 
$$-m_2 g \hat{j} - T \hat{e}_1 + f_2 \hat{e}_1 + N_2 \hat{e}_2 = \Sigma \vec{F}_2 = m_2 \vec{a}_2 = m_2 \ddot{x} \hat{e}_1$$

TAKE COMPONENTS IN  $(\hat{e}_1, \hat{e}_2)$  DIRECTIONS

$$\hat{j} = S_\phi \hat{e}_1 + C_\phi \hat{e}_2$$

BLOCK 1  $\hat{e}_1$  DIR: 
$$-m_1 g S_\phi + T + f_1 = m_1 \ddot{x}$$

$\hat{e}_2$  DIR: 
$$-m_1 g C_\phi + N_1 = 0$$

BLOCK 2  $\hat{e}_1$  DIR: 
$$-m_2 g S_\phi - T + f_2 = m_2 \ddot{x}$$

$\hat{e}_2$  DIR: 
$$-m_2 g C_\phi + N_2 = 0$$

UNKNOWN

$$\overleftarrow{T, f_1, \ddot{x}, N_1}$$

$$f_2, N_2$$

ELIMINATE  $T$  & SOLVE FOR  $(N_1, N_2)$

$$N_1 = m_1 g \cos \phi, \quad N_2 = m_2 g \cos \phi, \quad (m_1 + m_2) \ddot{x} = -(m_1 + m_2) g \sin \phi + f_1 + f_2$$

$$\uparrow \quad T = m_1 \ddot{x} - f_1 + m_1 g \sin \phi = \frac{m_1 f_2 - m_2 f_1}{(m_1 + m_2)}$$

SLIPPING DOWN ( $\dot{x} < 0$ )

$$f_1 = \mu_1 N_1 = \mu_1 m_1 g \cos \phi$$

$$f_2 = \mu_2 N_2 = \mu_2 m_2 g \cos \phi$$

$$T = \frac{(\mu_2 - \mu_1) m_1 m_2 g \cos \phi}{m_1 + m_2}$$

so

$$\ddot{x} = -g \sin \phi + \frac{(\mu_1 m_1 + \mu_2 m_2) g \cos \phi}{(m_1 + m_2)} \rightarrow a_1 = a_2 = \ddot{x} \hat{e}_1$$

STICK  $\ddot{x} = 0 \quad |f_i| \leq \mu_i N_i; \quad @ \quad \phi = \phi_* \quad f_1 = \mu_1 N_1, \quad f_2 = \mu_2 N_2$

$$0 = -(m_1 + m_2) g \sin \phi_* + (\mu_1 m_1 + \mu_2 m_2) g \cos \phi_* \rightarrow T_{\phi_*} = \frac{(\mu_1 m_1 + \mu_2 m_2) g \cos \phi_*}{m_1 + m_2}$$