

# Rigid Body Dynamics

## Engineering Mechanics: Dynamics

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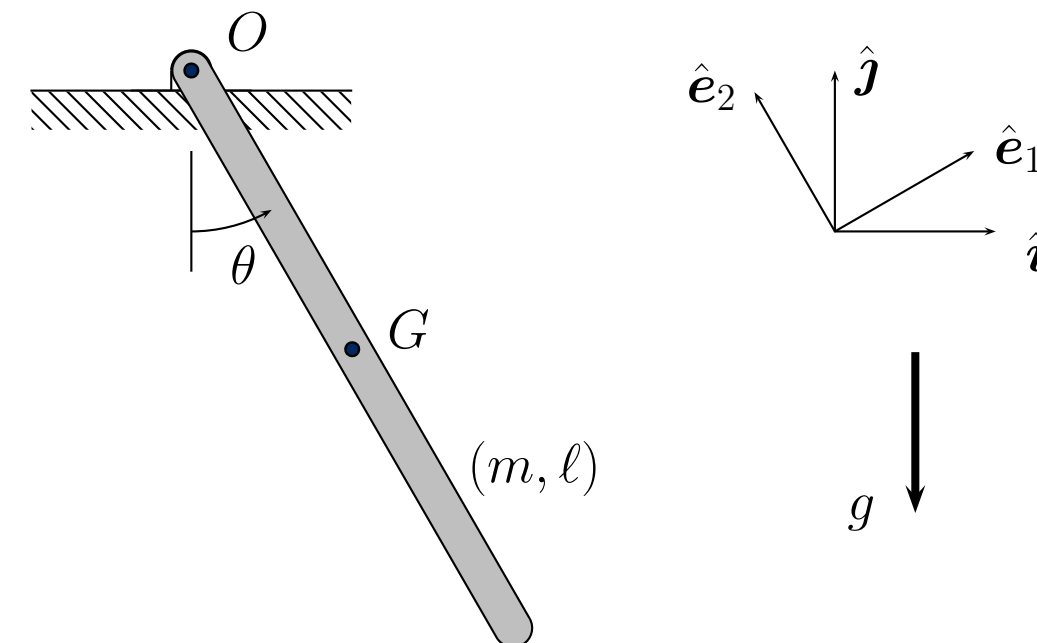
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The bar of mass  $m$  and length  $\ell$  is pinned at  $O$  and is released from rest at an angle  $\theta$ . Find its resulting angular acceleration at the instant it is released, as well as the reaction force at the pin.



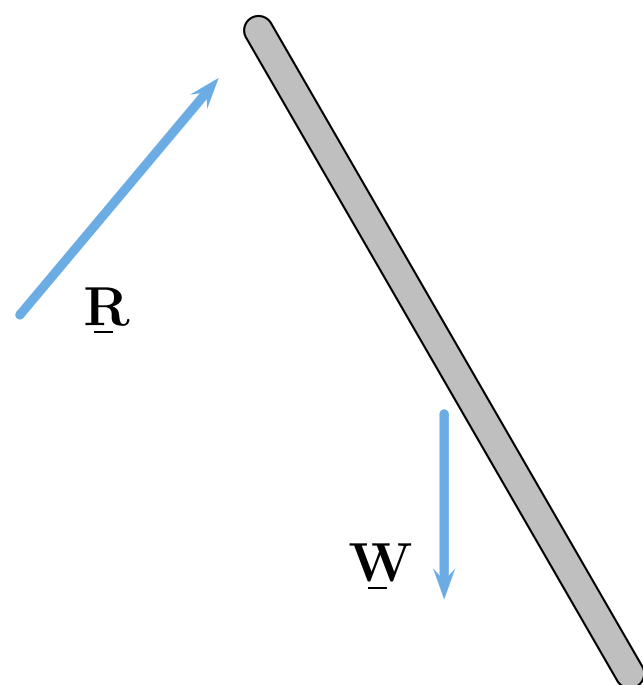
The bar is subject to forces arising from the

- ▶ Reaction force ( $\underline{\mathbf{R}}$ ) at the pin
- ▶ Weight ( $\underline{\mathbf{W}}$ )

### Coordinates and Directions

The coordinate  $\theta$  can be used to describe the configuration of the bar, so that

$$\hat{i} = C_{\theta} \hat{e}_1 - S_{\theta} \hat{e}_2, \quad \hat{j} = S_{\theta} \hat{e}_1 + C_{\theta} \hat{e}_2.$$



## Kinematics

The angular acceleration of the bar is  $\underline{\alpha}_B = \ddot{\theta} \hat{\mathbf{k}}$ , while the acceleration of the mass center  $G$  can be written as

$$\underline{\mathbf{a}}_G = \underline{\mathbf{a}}_O + \underline{\alpha}_B \times \underline{\mathbf{r}}_{G/O} + \underline{\omega}_B \times (\underline{\omega}_B \times \underline{\mathbf{r}}_{G/O}).$$

$O$  is pinned in the ground, so that  $\underline{\mathbf{a}}_O = \mathbf{0}$ , so that  $\underline{\mathbf{a}}_G$  can be written as

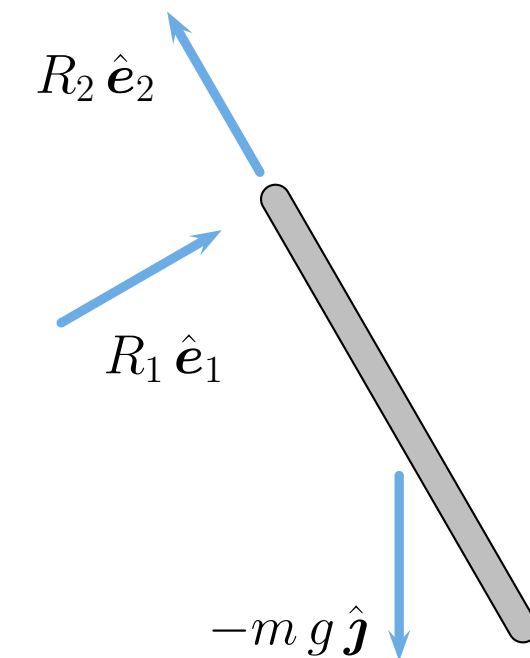
$$\underline{\mathbf{a}}_G = (\ddot{\theta} \hat{\mathbf{k}}) \times \left(-\frac{\ell}{2} \hat{\mathbf{e}}_2\right) + (\dot{\theta} \hat{\mathbf{k}}) \times \left( (\dot{\theta} \hat{\mathbf{k}}) \times \left(-\frac{\ell}{2} \hat{\mathbf{e}}_2\right) \right) = \frac{\ell \ddot{\theta}}{2} \hat{\mathbf{e}}_1 + \frac{\ell \dot{\theta}^2}{2} \hat{\mathbf{e}}_2.$$

Note that if the bar is released from rest  $\underline{\omega}_B = \mathbf{0}$ .

## Free Body Diagram

The free body diagram is shown to the right. Note that the unknown reaction force  $\underline{\mathbf{R}}$  has been decomposed into components in the  $(\hat{\mathbf{e}}_1, \hat{\mathbf{e}}_2)$  directions, so that

$$\underline{\mathbf{R}} = R_1 \hat{\mathbf{e}}_1 + R_2 \hat{\mathbf{e}}_2.$$



## Equations of Motion

Linear momentum balance for the bar can be written as

$$\sum \underline{\mathbf{F}} = R_1 \hat{\mathbf{e}}_1 + R_2 \hat{\mathbf{e}}_2 - m g \hat{\mathbf{j}} = \frac{m \ell \ddot{\theta}}{2} \hat{\mathbf{e}}_1 + \frac{m \ell \dot{\theta}^2}{2} \hat{\mathbf{e}}_2 = m \underline{\mathbf{a}}_G,$$

and taking components

$$\begin{aligned} \hat{\mathbf{e}}_1 \text{ direction:} & \quad R_1 - m g S_\theta = \frac{m \ell \ddot{\theta}}{2}, \\ \hat{\mathbf{e}}_2 \text{ direction:} & \quad R_2 - m g C_\theta = \frac{m \ell \dot{\theta}^2}{2}, \end{aligned}$$

Because the bar is pinned at  $O$  we take angular momentum balance about that point. The moment from the weight becomes

$$\underline{\mathbf{M}}_{\text{gravity}} = \underline{\mathbf{r}}_{G/O} \times \underline{\mathbf{W}} = \left( -\frac{\ell}{2} \hat{\mathbf{e}}_2 \right) \times (-m g \hat{\mathbf{j}}) = -\frac{m g \ell}{2} S_\theta \hat{\mathbf{k}},$$

so that angular momentum balance becomes

$$\sum \underline{\mathbf{M}}_O = -\frac{m g \ell}{2} S_\theta \hat{\mathbf{k}} = \frac{m \ell^2}{3} \ddot{\theta} \hat{\mathbf{k}} = I_O \underline{\boldsymbol{\alpha}}_B$$

Angular momentum balance yields

$$\ddot{\theta} = -\frac{3g}{2\ell} S_{\theta}, \quad \longrightarrow \quad \underline{\alpha}_B = \left( -\frac{3g}{2\ell} S_{\theta} \right) \hat{\mathbf{k}},$$

and finally the components of the reaction force are

$$\begin{aligned} R_1 &= m g S_{\theta} + \frac{m \ell}{2} \ddot{\theta}, & R_2 &= m g C_{\theta} + \frac{m \ell}{2} \dot{\theta}^2. \\ &= \frac{m g}{4} S_{\theta}, \end{aligned}$$

If the system is released from rest, then  $\dot{\theta} = 0$ , so that the reaction force is

$$\underline{\mathbf{R}} = R_1 \hat{\mathbf{e}}_1 + R_2 \hat{\mathbf{e}}_2 = \left( \frac{m g}{4} S_{\theta} \right) \hat{\mathbf{e}}_1 + (m g C_{\theta}) \hat{\mathbf{e}}_2.$$